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# **raytraverse Documentation**

***Release 0.2.4***

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raytraverse is a complete workflow for climate based daylight modelling, simulation, and evaluation of architectural spaces. Built around a variance based adaptive sampling strategy, raytraverse can fully explore the daylight conditions throughout a space with efficient use of processing power and storage space.

- Free software: Mozilla Public License 2.0 (MPL 2.0)
- Documentation: <https://raytraverse.readthedocs.io/en/v0.2.4/>.



## INSTALLATION

The easiest way to install raytraverse is with pip:

```
pip install --upgrade pip setuptools wheel
pip install raytraverse
```

or if you have cloned this repository:

```
cd path/to/this/file
pip install .
```

for a development install (pip install -e may not work correctly):

```
python setup.py develop
```

note that on first run one of the required modules may download some auxiliary data which could take a minute, after that first run start-up is much faster.





## USAGE

raytraverse includes a complete command line interface with all commands nested under the *raytraverse* parent command enter:

```
raytraverse --help
```

raytraverse also exposes an object oriented API written primarily in python. calls to Radiance are made through *Renderer* objects that wrap the radiance c source code in c++ classes, which are made available in python with *pybind11*. see the *src/* directory for more.

For complete documentation of the API and the command line interface either use the *Documentation* link included above or:

```
pip install -r docs/requirements.txt  
make docs
```

to generate local documentation.



## GIT STUFF

this project is hosted in two places, a private repo (master branch) at:

<https://gitlab.enterpriselab.ch/lightfields/raytraverse>

and a public repo (release branch) at:

<https://github.com/stephanwaz/raytraverse>

the repo also depends on two submodules, to initialize run the following:

```
git clone https://github.com/stephanwaz/raytraverse
cd raytraverse
git submodule init
git submodule update --remote
git -C src/Radiance config core.sparseCheckout true
cp src/sparse-checkout .git/modules/src/Radiance/info/
git submodule update --remote --force src/Radiance
```

after a “git pull” make sure you also run:

```
git submodule update
```

to track with the latest commit used by raytraverse.



**LICENCE**

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This Source Code Form is subject to the terms of the Mozilla Public License, v. 2.0. If a copy of the MPL was not distributed with this file, You can obtain one at <http://mozilla.org/MPL/2.0/>.



## CREDITS

This package was created with [Cookiecutter](#) and the [audreyr/cookiecutter-pypackage](#) project template.

## 5.1 raytraverse.scene

### 5.1.1 Scene

```
class raytraverse.scene.Scene(outdir, scene=None, area=None, reload=True, over-
                             write=False, ptres=1.0, ptro=0.0, pttol=1.0, viewdir=0, 1,
                             0, viewangle=360, skyres=10.0, maxspec=0.3, frozen=True,
                             **kwargs)
```

Bases: object

container for scene description

#### Parameters

- **outdir** (*str*) – path to store scene info and output files
- **scene** (*str, optional (required if not reload)*) – space separated list of radiance scene files (no sky) or octree
- **area** (*str, optional (required if not reload)*) – radiance scene file containing planar geometry of analysis area or a list of points (line per point, space separated, first 3 columns x, y, z)
- **reload** (*bool, optional*) – if True attempts to load existing scene files in new instance overrides ‘overwrite’
- **overwrite** (*bool, optional*) – if True and outdir exists, will overwrite, else raises a FileExistsError
- **ptres** (*float, optional*) – final spatial resolution in scene geometry units
- **ptro** (*float, optional*) – angle in degrees counter-clockwise to point grid
- **pttol** (*float, optional*) – tolerance for point search when using point list for area
- **viewdir** (*(float, float, float), optional*) – vector (x,y,z) view direction (orients UV space)
- **viewangle** (*float, optional*) – should be 1-180 or 360
- **skyres** (*float, optional*) – approximate square patch size (sets sun resolution too)
- **maxspec** (*float, optional*) – maximum specular transmission in scene (used to clip pdf for sun sampling)
- **frozen** (*bool, optional*) – create a frozen octree

**outdir** = None  
path to store scene info and output files  
**Type** str

**maxspec** = None  
maximum specular transmission in scene  
**Type** float

**reload** = None  
try to reload scene files  
**Type** bool

**view** = None  
view translation class  
**Type** raytraverse.viewmapper.ViewMapper

**property skyres**

**property scene**  
render scene files (octree)  
**Getter** Returns this samplers's scene file path  
**Setter** Sets this samplers's scene file path and creates run files  
**Type** str

**pts** ()

### 5.1.2 SunSetter

**class** raytraverse.scene.SunSetter (*scene, srct=0.01, skyro=0.0, reload=True, sunres=10.0, \*\*kwargs*)

Bases: object

select suns to sample based on sky pdf and scene.

#### Parameters

- **scene** (raytraverse.scene.Scene) – scene class containing geometry, location and analysis plane
- **srct** (float, optional) – threshold of sky contribution for determining appropriate srcn
- **skyro** (float, optional) – sky rotation (in degrees, ccw)
- **reload** (bool) – if True reloads existing sun positions, else always generates new

**srct** = None  
threshold of sky contribution for determining appropriate srcn  
**Type** float

**skyro** = None  
ccw rotation (in degrees) for sky  
**Type** float

**scene** = None  
raytraverse.scene.Scene

**property sunres**

**property sun\_kd**  
sun kdtree for directional queries



**property suns**

holds sun positions

**Getter** Returns the sun source array**Setter** Set the sun source array and write to files**Type** np.array**choose\_suns** ()**load\_sky\_facs** ()**direct\_view** ()**write\_sun** (i)**proxy\_src** (tsuns, tol=10.0)

check if sun directions have matching source in SunSetter

**Parameters**

- **tsuns** (np.array) – (N, 3) array containing sun source vectors to check
- **tol** (float) – tolerance (in degrees)

**Returns**

- np.array – (N,) index to proxy src
- list – (N,) error in degrees to proxy sun

**\_write\_suns** (sunfile)

write suns to file

**Parameters** sunfile –

### 5.1.3 SunSetterLoc

**class** raytraverse.scene.SunSetterLoc (scene, loc, skyro=0.0, \*\*kwargs)

Bases: raytraverse.scene.sunsetter.SunSetter

select suns to sample based on sky pdf and scene.

**Parameters**

- **scene** (raytraverse.scene.Scene) – scene class containing geometry, location and analysis plane
- **loc** (tuple) – lat, lon, tz (in degrees, west is positive)
- **srct** (float, optional) – threshold of sky contribution for determining appropriate srcn
- **skyro** (float, optional) – sky rotation (in degrees, ccw)
- **reload** (bool) – if True reloads existing sun positions, else always generates new

**sky = None**

raytraverse.scene.SkyInfo

**choose\_suns** ()

### 5.1.4 SunSetterPositions

**class** raytraverse.scene.SunSetterPositions (*scene*, *wea*, *skyro*=0.0, *\*\*kwargs*)

Bases: raytraverse.scene.sunsetter.SunSetter

select suns to sample based on sky pdf and scene.

#### Parameters

- **scene** (raytraverse.scene.Scene) – scene class containing geometry, location and analysis plane
- **wea** (*str*, *np.array*, *optional*) – path to sun position file or wea file, or array of sun positions
- **srct** (*float*, *optional*) – threshold of sky contribution for determining appropriate srcn
- **skyro** (*float*, *optional*) – sky rotation (in degrees, ccw)
- **reload** (*bool*) – if True reloads existing sun positions, else always generates new

**scene** = None

raytraverse.scene.Scene

**skyro** = None

ccw rotation (in degrees) for sky

**Type** float

**property candidates**

raytraverse.scene.SkyInfo

**choose\_suns** ()

### 5.1.5 SkyInfo

**class** raytraverse.scene.SkyInfo (*loc*, *skyro*=0.0)

Bases: object

sky location data object

#### Parameters

- **loc** (*tuple*) – lat, lon, tz (in degrees, west is positive)
- **skyro** (*float*) – sky rotation (in degrees, ccw)

**skyro** = None

ccw rotation (in degrees) for sky

**Type** float

**property solarbounds**

read only extent of solar bounds for given location set via loc

**Getter** Returns solar bounds

**Type** (np.array, np.array)

**property loc**

scene location

**Getter** Returns location

**Setter** Sets location and self.solarbounds

**Type** (float, float, int)

**in\_solarbounds** (*uv, size=0.0*)  
for checking if src direction is in solar transit

**Parameters**

- **uv** (*np.array*) – source directions
- **size** (*float*) – offset around UV to test

**Returns result** – Truth of ray.src within solar transit

**Return type** np.array

## 5.2 raytraverse.mapper

### 5.2.1 SpaceMapper

**class** raytraverse.mapper.**SpaceMapper** (*dfile, ptres=1.0, rotation=0.0, tolerance=1.0*)

Bases: object

translate between world coordinates and normalized UV space

**rotation = None**

ccw rotation (in degrees) for point grid on plane

**Type** float

**tolerance = None**

tolerance for point search when using point list for area

**Type** float

**ptres = None**

point resolution for area

**Type** float

**property pt\_kd**

point kdtree for spatial queries built at first use

**property sf**

bbox scale factor

**property ptshape**

shape of point grid

**property npts**

number of points

**property bbox**

boundary frame for translating between coordinates [[xmin ymin zmin] [xmax ymax zmax]]

**Type** np.array

**\_ro\_pts** (*points, rdir=-1*)

rotate points

**Parameters**

- **points** (*np.ndarray*) – world coordinate points of shape (N, 3)
- **rdir** (*-1 or 1*) –

**rotation direction:** -1 to rotate from uv space 1 to rotate to uvspace

**uv2pt** (*uv*)

convert UV → world

**Parameters uv** (*np.array*) – normalized UV coordinates of shape (N, 2)

**Returns** **pt** – world xyz coordinates of shape (N, 3)

**Return type** np.array

**pt2uv** (*xyz*)

convert world → UV

**Parameters** **xyz** (*np.array*) – world xyz coordinates, shape (N, 3)

**Returns** **uv** – normalized UV coordinates of shape (N, 2)

**Return type** np.array

**idx2pt** (*idx*)

**pts** ()

**in\_area** (*xyz*)

check if point is in boundary path

**Parameters** **xyz** (*np.array*) – uv coordinates, shape (N, 3)

**Returns** **mask** – boolean array, shape (N,)

**Return type** np.array

**\_rad\_scene\_to\_bbox** (*plane*)

## 5.2.2 SpaceMapperPt

**class** raytraverse.mapper.SpaceMapperPt (*dfile, ptres=1.0, rotation=0.0, tolerance=1.0*)

Bases: raytraverse.mapper.spacemapper.SpaceMapper

translate between world coordinates and normalized UV space

**property** **sf**

bbox scale factor

**property** **ptshape**

shape of point grid

**property** **bbox**

bounding box

**Type** np.array of shape (3,2)

**uv2pt** (*uv*)

convert UV → world

**Parameters** **uv** (*np.array*) – normalized UV coordinates of shape (N, 2)

**Returns** **pt** – world xyz coordinates of shape (N, 3)

**Return type** np.array

**pt2uv** (*xyz*)

convert world → UV

**Parameters** **xyz** (*np.array*) – world xyz coordinates, shape (N, 3)

**Returns** **uv** – normalized UV coordinates of shape (N, 2)

**Return type** np.array

**idx2pt** (*idx*)

**pts** ()

**in\_area** (*xyz*)

check if point is in boundary path

**Parameters** **xyz** (*np.array*) – uv coordinates, shape (N, 3)

**Returns** `mask` – boolean array, shape (N,)

**Return type** `np.array`

### 5.2.3 ViewMapper

**class** `raytraverse.mapper.ViewMapper` (*dxyz=0.0, 1.0, 0.0, viewangle=360.0, name='view',  
mtxs=None, imtxs=None*)

Bases: `object`

translate between world and normalized UV space based on direction and view angle

#### Parameters

- **dxyz** (*tuple, optional*) – central view direction
- **viewangle** (*float, optional*) – if < 180, the horizontal and vertical view angle, if greater, view becomes 360,180

**property viewangle**

view angle

**property ymtx**

yaw rotation matrix (to standard z-direction y-up)

**property pmtx**

pitch rotation matrix (to standard z-direction y-up)

**property bbox**

bounding box of view

**Type** `np.array` of shape (2,2)

**property sf**

bbox scale factor

**property ivm**

viewmapper for opposite view direction (in case of 360 degree view)

**property dxyz**

(float, float, float) central view direction

**view2world** (*xyz, i=0*)

**world2view** (*xyz, i=0*)

**xyz2uv** (*xyz, i=0*)

**uv2xyz** (*uv, i=0*)

**xyz2xy** (*xyz, i=0*)

**pixelrays** (*res, i=0*)

**ray2pixel** (*xyz, res, i=0*)

**pixel2ray** (*pxy, res, i=0*)

**pixel2omega** (*pxy, res*)

**ctheta** (*vec, i=0*)

**radians** (*vec, i=0*)

**degrees** (*vec, i=0*)

**in\_view** (*vec, i=0, indices=True*)

## 5.2.4 SunMapper

**class** raytraverse.mapper.**SunMapper** (*suns*)  
Bases: raytraverse.mapper.viewmapper.ViewMapper  
translate between view and normalized UV space  
**Parameters** **suns** (*np.array*) – dx,dy,dz sun positions

## 5.3 raytraverse.renderer

### 5.3.1 Renderer

### 5.3.2 RadianceRenderer

### 5.3.3 Rtrace

### 5.3.4 Rcontrib

### 5.3.5 SPRenderer

### 5.3.6 SPRtrace

### 5.3.7 SPRcontrib

## 5.4 raytraverse.sampler

### 5.4.1 Sampler

### 5.4.2 SCBinSampler

### 5.4.3 SunSampler

### 5.4.4 SingleSunSampler

### 5.4.5 SunViewSampler

## 5.5 raytraverse.lightfield

### 5.5.1 LightField

### 5.5.2 LightFieldKD

### 5.5.3 SCBinField

### 5.5.4 SunField

### 5.5.5 SunSkyPt

### 5.5.6 SunViewField

### 5.5.7 MemArrayDict

```
class raytraverse.lightfield.memarraydict.MemArrayDict
```

```
    Bases: dict
```

```
    a dictionary like object that holds arguments for numpy.memmap, the getter returns a view to the array
```

```
    static _map(i)
```

```
    values() → an object providing a view on D's values
```

```
constructors ()
full_array ()
full_constructor ()
index_strides ()
```

## 5.6 raytraverse.integrator

### 5.6.1 Integrator

## 5.7 raytraverse.craytraverse

## 5.8 raytraverse.draw

## 5.9 raytraverse.io

functions for reading and writing

```
class raytraverse.io.CaptureStdOut (b=False, store=True, outf=None)
    Bases: object
```

redirect output streams at system level (including c printf)

#### Parameters

- **b** (*bool, optional*) – read data as bytes
- **store** (*bool, optional*) – record stdout in a IOStream, value accesible through self.stdout
- **outf** (*IOBase, optional*) – if not None, must be writable, closed on exit

#### Notes

```
with CaptureStdOut() as capture:
    do stuff
capout = capture.stdout
```

when using with pytest include the -s flag or this class has no effect

#### property stdout

```
drain_bytes ()
    read stdout as bytes
```

```
drain_str ()
    read stdout as unicode
```

```
raytraverse.io.get_nproc (nproc=None)
```

```
raytraverse.io.set_nproc (nproc)
```

```
raytraverse.io.unset_nproc ()
```

```
raytraverse.io.call_sampler (outf, command, vecs, shape)
```

make subprocess call to sampler given as command, expects rgb value as return for each vec

#### Parameters

- **outf** (*str*) – path to write out to



- **command** (*str*) – command line with executable and options
- **vecs** (*np.array*) – vectors to pass as stdin to command
- **shape** (*tuple*) – shape of expected output

**Returns** *lums* – of length *vectors.shape[0]*

**Return type** *np.array*

`raytraverse.io.bytefile2rad` (*f, shape, slc=Ellipsis, subs='ijk,k->ij', offset=0*)

`raytraverse.io.np2bytes` (*ar, dtype='<f'*)  
format *ar* as bytestring

**Parameters**

- **ar** (*np.array*) –
- **dtype** (*str*) – argument to pass to *np.dtype()*

**Returns**

**Return type** *bytes*

`raytraverse.io.bytes2np` (*buf, shape, dtype='<f'*)  
read *ar* from bytestring

**Parameters**

- **buf** (*bytes, str*) –
- **shape** (*tuple*) – array shape
- **dtype** (*str*) – argument to pass to *np.dtype()*

**Returns**

**Return type** *np.array*

`raytraverse.io.bytefile2np` (*f, shape, dtype='<f'*)  
read binary data from *f*

**Parameters**

- **f** (*IOBase*) – file object to read array from
- **shape** (*tuple*) – array shape
- **dtype** (*str*) – argument to pass to *np.dtype()*

**Returns** necessary for reconstruction

**Return type** *ar.shape*

`raytraverse.io.array2hdr` (*ar, imgf, header=None*)  
write 2d *np.array* (*x,y*) to *hdr* image format

**Parameters**

- **ar** (*np.array*) –
- **imgf** (*file path to right*) –
- **header** (*list of header lines to append to image header*) –

`raytraverse.io.carray2hdr` (*ar, imgf, header=None*)  
write color channel *np.array* (*3, x, y*) to *hdr* image format

**Parameters**

- **ar** (*np.array*) –
- **imgf** (*file path to right*) –
- **header** (*list of header lines to append to image header*) –

`raytraverse.io.hdr2array (imgf)`

read np.array from hdr image

**Parameters** `imgf` (*file path of image*) –

**Returns** `ar`

**Return type** `np.array`

`raytraverse.io.rgb2lum (rgbe)`

convert from Radiance hdr rgbe 4-byte data format to floating point luminance.

**Parameters** `rgbe` (*np.array*) – r,g,b,e unsigned integers according to: <http://radsite.lbl.gov/radiance/refer/filefmts.pdf>

**Returns** `lum`

**Return type** luminance in  $\text{cd/m}^2$

`raytraverse.io.add_vecs_to_img (vm, img, v, channels=1, 0, 0, grow=0)`

## 5.10 raytraverse.metricfuncs

standardized metric functions

`raytraverse.metricfuncs.illum (vm, vec, omega, lum, scale=179, **kwargs)`

`raytraverse.metricfuncs.avglum (vm, vec, omega, lum, scale=179, area=None, **kwargs)`

`raytraverse.metricfuncs.sqglum (vm, vec, omega, lum, scale=179, area=None, **kwargs)`

`raytraverse.metricfuncs.to_plane (n, vec)`

`raytraverse.metricfuncs.angle_vv (a, b)`

`raytraverse.metricfuncs.get_pid_x_guth (sigma, tau)`

`raytraverse.metricfuncs.get_pid_x_iwata (phi, theta)`

`raytraverse.metricfuncs.get_pid_x_kim (sigma, tau)`

`raytraverse.metricfuncs.get_pos_idx (vm, vec, guth=True)`

## 5.11 raytraverse.plot

functions for plotting data

`raytraverse.plot.save_img (fig, ax, outf, title=None)`

`raytraverse.plot.imshow (im, figsize=10, 10, outf=None, **kwargs)`

`raytraverse.plot.mk_img_setup (lums, bounds=None, figsize=10, 10, ext=1)`

`raytraverse.plot.set_ang_ticks (ax, ext)`

`raytraverse.plot.colormap (colors, norm)`

`raytraverse.plot.plot_patches (ax, patches, patchargs=None)`

## 5.12 raytraverse.quickplot

functions for plotting data

`raytraverse.quickplot.imshow(im, figsize=10, 10, outf=None, **kwargs)`

`raytraverse.quickplot.hist(lums, bins='auto', outf=None, **kwargs)`

## 5.13 raytraverse.skycalc

functions for loading sky data and computing sun position

`raytraverse.skycalc.read_epw(epw)`

read daylight sky data from epw or wea file

**Returns** `out` – (month, day, hour, dirnorn, difhoriz)

**Return type** `np.array`

`raytraverse.skycalc.get_loc_epw(epw, name=False)`

get location from epw or wea header

`raytraverse.skycalc.sunpos_utc(timesteps, lat, lon, builtin=True)`

Calculate sun position with local time

Calculate sun position (altitude, azimuth) for a particular location (longitude, latitude) for a specific date and time (time is in UTC)

### Parameters

- **timesteps** (`np.array(datetime.datetime)`) –
- **lon** (`float`) – longitude in decimals. West is +ve
- **lat** (`float`) – latitude in decimals. North is +ve
- **builtin** (`bool`) – use skyfield builtin timescale

### Returns

- (`skyfield.units.Angle`, `skyfield.units.Angle`)
- altitude and azimuth in degrees

`raytraverse.skycalc.row_2_datetime64(ts, year=2020)`

`raytraverse.skycalc.datetime64_2_datetime(timesteps, mer=0.0)`

convert datetime representation and offset for timezone

### Parameters

- **timesteps** (`np.array(np.datetime64)`) –
- **mer** (`float`) – Meridian of the time zone. West is +ve

### Returns

**Return type** `np.array(datetime.datetime)`

`raytraverse.skycalc.sunpos_degrees(timesteps, lat, lon, mer, builtin=True, ro=0.0)`

Calculate sun position with local time

Calculate sun position (altitude, azimuth) for a particular location (longitude, latitude) for a specific date and time (time is in local time)

### Parameters

- **timesteps** (`np.array(np.datetime64)`) –
- **lon** (`float`) – longitude in decimals. West is +ve

- **lat** (*float*) – latitude in decimals. North is +ve
- **mer** (*float*) – Meridian of the time zone. West is +ve
- **builtin** (*bool, optional*) – use skyfield builtin timescale
- **ro** (*float, optional*) – ccw rotation (project to true north) in degrees

**Returns** Sun position as (altitude, azimuth) in degrees

**Return type** `np.array([float, float])`

`raytraverse.skycalc.sunpos_radians (timesteps, lat, lon, mer, builtin=True, ro=0.0)`

Calculate sun position with local time

Calculate sun position (altitude, azimuth) for a particular location (longitude, latitude) for a specific date and time (time is in local time)

#### Parameters

- **timesteps** (`np.array(np.datetime64)`) –
- **lon** (*float*) – longitude in decimals. West is +ve
- **lat** (*float*) – latitude in decimals. North is +ve
- **mer** (*float*) – Meridian of the time zone. West is +ve
- **builtin** (*bool*) – use skyfield builtin timescale
- **ro** (*float, optional*) – ccw rotation (project to true north) in radians

**Returns** Sun position as (altitude, azimuth) in radians

**Return type** `np.array([float, float])`

`raytraverse.skycalc.sunpos_xyz (timesteps, lat, lon, mer, builtin=True, ro=0.0)`

Calculate sun position with local time

Calculate sun position (altitude, azimuth) for a particular location (longitude, latitude) for a specific date and time (time is in local time)

#### Parameters

- **timesteps** (`np.array(np.datetime64)`) –
- **lon** (*float*) – longitude in decimals. West is +ve
- **lat** (*float*) – latitude in decimals. North is +ve
- **mer** (*float*) – Meridian of the time zone. West is +ve
- **builtin** (*bool*) – use skyfield builtin timescale
- **ro** (*float, optional*) – ccw rotation (project to true north) in degrees

**Returns** Sun position as (x, y, z)

**Return type** `np.array`

`raytraverse.skycalc.generate_wea (ts, wea, interp='linear')`

`raytraverse.skycalc.coeff_lum_perez (sunz, epsilon, delta, catn)`  
matches `coeff_lum_perez` in `gendaylit.c`

`raytraverse.skycalc.perez_apply_coef (coefs, cgamma, dz)`

`raytraverse.skycalc.perez_lum_raw (tp, dz, sunz, coefs)`  
matches `calc_rel_lum_perez` in `gendaylit.c`

`raytraverse.skycalc.perez_lum (xyz, coefs)`  
matches `perezlum.cal`

`raytraverse.skycalc.perez (sxyz, dirdif, md=None, ground_fac=0.2)`  
compute perez coefficients

## Notes

to match the results of gendaylit, for a given sun angle without associated date, the assumed eccentricity is 1.035020

### Parameters

- **sxyz** (*np.array*) – (N, 3) dx, dy, dz sun position
- **dirdif** (*np.array*) – (N, 2) direct normal, diffuse horizontal W/m<sup>2</sup>
- **md** (*np.array*, *optional*) – (N, 2) month day of sky calcs (for more precise eccentricity calc)
- **ground\_fac** (*float*) – scaling factor (reflecctance) for ground brightness

**Returns** **perez** – (N, 10) diffuse normalization, ground brightness, perez coefs, x, y, z

**Return type** *np.array*

`raytraverse.skycalc.sky_mtx(sxyz, dirdif, side, jn=4, ground_fac=0.2)`  
generate sky, ground and sun values from sun position and sky values

### Parameters

- **sxyz** (*np.array*) – sun directions (N, 3)
- **dirdif** (*np.array*) – direct normal and diffuse horizontal radiation (W/m<sup>2</sup>) (N, 2)
- **side** (*int*) – sky subdivision
- **jn** (*int*) – sky patch subdivision  $n = jn^2$
- **ground\_fac** (*float*) – scaling factor (reflecctance) for ground brightness

### Returns

- **skymtx** (*np.array*) – (N, side\*side)
- **grndval** (*np.array*) – (N,)
- **sunval** (*np.array*) – (N, 4) - sun direction and radiance

## 5.14 raytraverse.translate

functions for translating between coordinate spaces and resolutions

`raytraverse.translate.norm(v)`  
normalize 2D array of vectors along last dimension

`raytraverse.translate.norm1(v)`  
normalize flat vector

`raytraverse.translate.tpnorm(thetaphi)`  
normalize angular vector to 0-pi, 0-2pi

`raytraverse.translate.uv2xy(uv)`  
translate from unit square (0,1),(0,1) to disk (x,y) <http://psgraphics.blogspot.com/2011/01/improved-code-for-concentric-map.html>.

`raytraverse.translate.uv2xyz(uv, axes=0, 1, 2, xsign=-1)`  
translate from 2 x unit square (0,2),(0,1) to unit sphere (x,y,z) <http://psgraphics.blogspot.com/2011/01/improved-code-for-concentric-map.html>.

`raytraverse.translate.xyz2uv(xyz, normalize=False, axes=0, 1, 2, flipu=True)`  
translate from vector x,y,z (normalized) to u,v (0,2),(0,1) Shirley, Peter, and Kenneth Chiu. A Low Distortion Map Between Disk and Square. Journal of Graphics Tools, vol. 2, no. 3, Jan. 1997, pp. 45-52. Taylor and Francis+NEJM, doi:10.1080/10867651.1997.10487479.

`raytraverse.translate.xyz2xy` (*xyz, axes=0, 1, 2, flip=True*)  
`raytraverse.translate.pxy2xyz` (*pxy, viewangle=180.0*)  
`raytraverse.translate.tp2xyz` (*thetaphi, normalize=True*)  
calculate x,y,z vector from theta (0-pi) and phi (0-2pi) RHS Z-up  
`raytraverse.translate.xyz2tp` (*xyz*)  
calculate theta (0-pi), phi from x,y,z RHS Z-up  
`raytraverse.translate.tp2uv` (*thetaphi*)  
calculate UV from theta (0-pi), phi  
`raytraverse.translate.uv2tp` (*uv*)  
calculate theta (0-pi), phi from UV  
`raytraverse.translate.uv2ij` (*uv, side*)  
`raytraverse.translate.uv2bin` (*uv, side*)  
`raytraverse.translate.bin2uv` (*bn, side*)  
`raytraverse.translate.bin_borders` (*sb, side*)  
`raytraverse.translate.resample` (*samps, ts=None, gauss=True, radius=None*)  
simple array resampling. requires whole number multiple scaling.

**Parameters**

- **samps** (*np.array*) – array to resample along each axis
- **ts** (*tuple, optional*) – shape of output array, should be multiple of samps.shape
- **gauss** (*bool, optional*) – apply gaussian filter to upsampling
- **radius** (*float, optional*) – when gauss is True, filter radius, default is the scale ratio - 1

**Returns** to resampled array

**Return type** `np.array`

`raytraverse.translate.interpolate2d` (*a, s*)  
`raytraverse.translate.rmtx_elem` (*theta, axis=2, degrees=True*)  
`raytraverse.translate.rotate_elem` (*v, theta, axis=2, degrees=True*)  
`raytraverse.translate.rmtx_yp` (*v*)  
generate a pair of rotation matrices to transform from vector *v* to *z*, enforcing a *z*-up in the source space and a *y*-up in the destination. If *v* is *z*, returns pair of identity matrices, if *v* is *-z* returns pair of 180 degree rotation matrices.

**Parameters** *v* (*array-like of size (3,)*) – the vector direction representing the starting coordinate space

**Returns** *ymtx*, *pmtx* – two rotation matrices to be premultiplied in order to reverse transform, swap order and transpose. Forward: `pmtx@(ymtx@xyz.T)).T` Backward: `ymtx.T@(pmtx.T@xyz.T)).T`

**Return type** (`np.array`, `np.array`)

`raytraverse.translate.chord2theta` (*c*)  
compute angle from chord on unit circle

**Parameters** *c* (*float*) – chord or euclidean distance between normalized direction vectors

**Returns** *theta* – angle captured by chord

**Return type** `float`

`raytraverse.translate.theta2chord` (*theta*)  
compute chord length on unit sphere from angle

**Parameters** `theta` (*float*) – angle

**Returns** `c` – chord or euclidean distance between normalized direction vectors

**Return type** float

`raytraverse.translate.aa2xyz(aa)`

`raytraverse.translate.xyz2aa(xyz)`

## 5.15 History

### 5.15.1 0.2.0 (2020-09-25)

- Build now includes all radiance dependencies to setup multi-platform testing
- In the absence of raytraverse, sampler falls back to SPRenderer
- install process streamlined for developer mode
- travis ci deploys linux and mac wheels directly to pypi
- **release.sh should be run after updating this file, tests past locally and** docs build.

### 5.15.2 0.1.0 (2020-05-19)

- First release on PyPI.

## 5.16 Index

## 5.17 Search

## 5.18 Todo





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